- (b) The criteria specified in paragraph (a) of this section are limited in application to the conditions of loading and operation of vessels for which the righting arm (GZ) at the angle (T), calculated after the vessel is permitted to trim free until the trimming moment is zero, is not less than the minimum metacentric height (GM) calculated in paragraph (a) of this section multiplied by sin(T). In conditions not meeting this requirement, the Coast Guard Marine Safety Center requires calculations in addition to those in this section.
- (c) A vessel that complies with the requirements for passenger ships contained in the International Code of Intact Stability, 2008 (2008 IS Code) (incorporated by reference, see §171.012) need not comply with paragraphs (a) or (b) of this section. Vessels complying with the 2008 IS Code must use the Assumed Average Weight per Person obtained according to §170.090 of this title to be exempt from the other requirements of this section.

 $[{\tt USCG-2007-0030,\,75\;FR\;78085,\,Dec.\,14,\,2010}]$

§ 171.052 Passenger heel requirements for pontoon vessels.

- (a) Each pontoon vessel, in each condition of loading and operation, must have an area under the righting arm curve from the angle of equilibrium to an angle of 40 degrees, the downflooding angle, or the angle of the maximum righting arm, whichever is less, of at least:
- (1) For operation on exposed or partially protected waters—
- (i) 10 foot-degrees with a crowding density of 5 square feet per person (2.15 persons per square meter); and
- (ii) 7 foot-degrees with a crowding density of 2 square feet per person (5.38 persons per square meter); and
- (2) For operation on protected waters—
- (i) 5 foot-degrees with a crowding density of 5 square feet per person (2.15 persons per square meter); and
- (ii) 2 foot-degrees with a crowding density of 2 square feet per person (5.38 persons per square meter).
- (b) When assessing compliance with the criteria of this section, passengers are assumed to be distributed in all areas accessible to passengers so as to

produce the most unfavorable combination of heel and trim.

[USCG-2007-0030, 75 FR 78085, Dec. 14, 2010]

§171.055 Intact stability requirements for a monohull sailing vessel or a monohull auxiliary sailing vessel.

- (a) Except as specified in paragraph (b) of this section, each monohull sailing vessel and auxiliary sailing vessel must be shown by design calculations to meet the stability requirements in this section.
- (b) Additional or different stability requirements may be needed for a vessel of unusual form, proportion, or rig. The additional requirements, if needed, will be prescribed by the Commandant.
- (c) Each vessel must have positive righting arms in each condition of loading and operation from—
- (1) 0 to at least 70 degrees of heel for service on protected or partially protected waters; and
- (2) 0 to at least 90 degrees of heel for service on exposed waters.
- (d) Each vessel must be designed to satisfy the following equations:
- (1) For a vessel in service on protected or partially protected waters—

$$\frac{1000(W)HZA}{(A)(H)} \ge X$$

$$\frac{1000(W)HZB}{(A)(H)} \ge Y$$

$$\frac{1000(W)HZC}{(A)(H)} \ge Z$$

where-

X=1.0 long tons/sq. ft. (10.9 metric tons/sq. meter).

Y=1.1 long tons/sq. ft. (12.0 metric tons/sq. meter).

Z=1.25 long tons/sq. ft. (13.7 metric tons/sq. meter).

(2) For a vessel on exposed waters—

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$$\frac{1000(W)HZA}{(A)(H)} \ge X$$

$$\frac{1000(W)HZB}{(A)(H)} \ge Y$$

$$\frac{1000(W)HZC}{(A)(H)} \ge Z$$

where-

HZA, HZB, and HZC are calculated in the manner specified in paragraph (e) or (f) of this section.

X=1.5 long tons/sq. ft. (16.4 metric tons/sq. meter).

Y=1.7 long tons/sq. ft. (18.6 metric tons/sq. meter).

Z=1.9 long tons/sq. ft. (20.8 metric tons/sq. meter).

A=the projected lateral area or silhouette in square feet (meters) of the portion of the vessel above the waterline computed with all sail set and trimmed flat. Sail overlap areas need not be included except parachute type spinnakers which are to be added regardless of overlap.

H=the vertical distance in feet (meters) from the center of A to the center of the underwater lateral area or approximately to the one-half draft point.

W=the displacement of the vessel in long (metric) tons.

- (e) Except as provided in paragraph (f) of this section, HZA, HZB, and HZC must be determined as follows for each condition of loading and operation:
- (1) Plot the righting arm curve on Graphs 171.055 (b), (c), and (d) or (e).
- (2) If the angle at which the maximum righting arm occurs is less than 35 degrees, the righting arm curve must be truncated as shown on Graph 171.055(a).
- (3) Plot an assumed heeling arm curve on Graph 171.055(b) that satisfies the following conditions:
- (i) The assumed heeling arm curve must be defined by the equation—

HZ=HZA cos² (T)

where-

where— HZ=heeling arm. HZA=heeling arm at 0 degrees of heel. T=angle of heel.

- (ii) The first intercept shown on Graph 171.055(b) must occur at the angle of heel corresponding to the angle at which deck edge immersion first occurs.
- (4) Plot an assumed heeling arm curve on Graph 171.055(c) that satisfies the following conditions:
- (i) The assumed heeling arm curve must be defined by the equation—

HZ=HZB cos² (T)

where-

HZ=heeling arm.

HZB=heeling arm at 0 degrees of heel. T=angle of heel.

- (ii) The area under the assumed heeling arm curve between 0 degrees and the downflooding angle or 60 degrees, whichever is less, must be equal to the area under the righting arm curve between the same limiting angles.
- (5) Plot an assumed heeling arm curve on Graph 171.055 (d) or (e) that satisfies the following conditions:
- (i) The assumed heeling arm curve must be defined by—

HZ=HZC cos2 (T)

where-

HZ=heeling arm.

HZC=heeling arm at 0 degrees of heel. T=angle of heel.

(ii) The area under the assumed heeling arm curve between the angles of 0 and 90 degrees must be equal to the

tween 0 degrees and—
(A) 90 degrees if the righting arms are positive to an angle less than or equal to 90 degrees; or

area under the righting arm curve be-

- (B) The largest angle corresponding to a positive righting arm but no more than 120 degrees if the righting arms are positive to an angle greater than 90 degrees.
- (6) The values of HZA, HZB, and HZC are read directly from Graphs 171.055 (b), (c), and (d) or (e).
- (f) For the purpose of this section, the downflooding angle means the static angle from the intersection of the vessel's centerline and waterline in calm water to the first opening that cannot be rapidly closed watertight.
- (g) HZB and, if the righting arms are positive to an angle of 90 degrees or greater, HZC may be computed from the following equation:

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HZB (or HZC) =
$$\frac{I}{((T/2)+14.3\sin 2T)}$$

where-

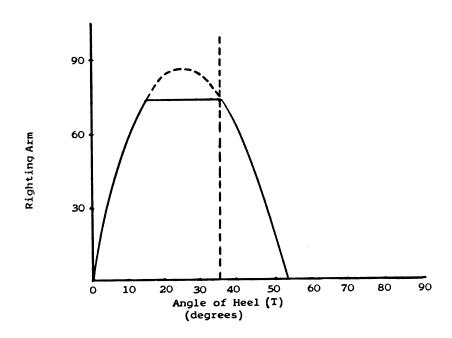
I=the area under the righting arm curve to—
(1) the downflooding angle or 60 degrees,
whichever is less, when computing HZB;
or

(2) the largest angle corresponding to a positive righting arm or 90 degrees, whichever is greater, but no greater than 120 degrees when computing HZC.

T=the downflooding angle or 60 degrees, whichever is less, when computing HZB or 90 degrees when computing HZC.

GRAPH 171.055(a)

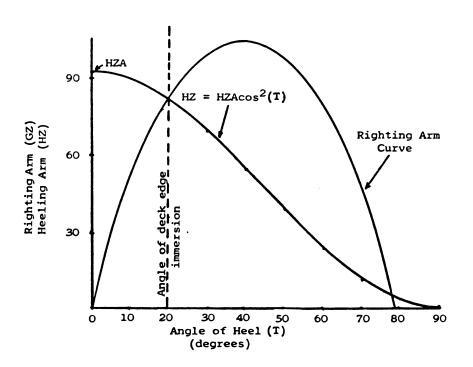
Truncation of Righting Arm Curve if Maximum Righting Arm Occurs at an Angle of Heel Less Than 35 Degrees



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GRAPH 171.055(b)

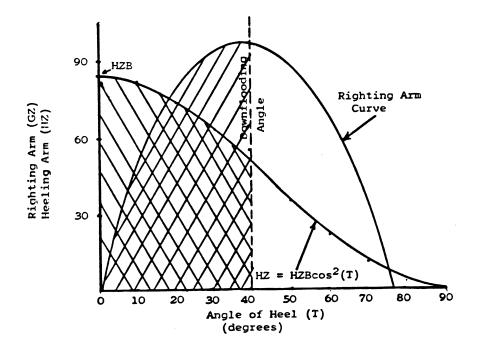
First Intercept Occurs at the Angle at Which Deck Edge Immersion First Occurs



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GRAPH 171.055(c)

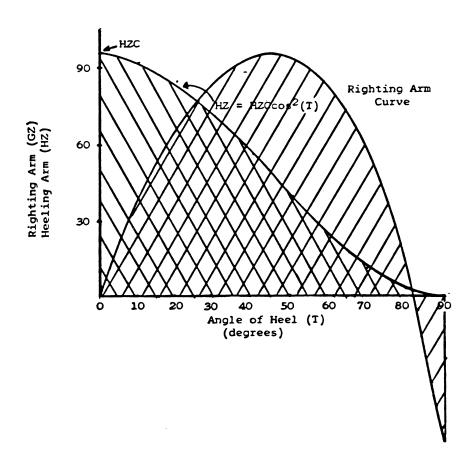
Shaded Areas are Balanced to the Downflooding Angle



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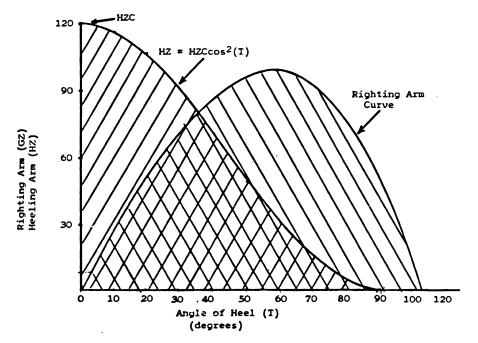
GRAPH 171.055(d)

$\frac{\text{Righting Arm Curve is not Positive to 90 Degrees and Negative}}{\underline{\text{Area is Included}}}$



GRAPH 171.055(e)

Righting Arm Curve is Positive Beyond 90 Degrees



 $[\text{CGD } 79\text{--}023, \, 48 \,\, \text{FR } 51017, \, \text{Nov. } 4, \, 1983, \, \text{as amended by CGD } 83\text{--}005, \, 51, \, \text{FR } 924, \, \text{Jan. } 9, \, 1986]$

§ 171.057 Intact stability requirements for a sailing catamaran.

(a) A sailing vessel that operates on protected waters must be designed to satisfy the following equation:

$$\frac{0.1(W)B}{(As)(Hc)} \ge X$$

Where-

B=the distance between hull centerlines in meters (feet).

As=the maximum sail area in square meters (square feet).

He=the height of the center of effort of the sail area above the deck, in meters (feet).

W=the total displacement of the vessel, in kilograms (pounds).

X=4.88 kilograms/square meter (1.0 pounds/square foot).

(b) A sailing vessel that operates on partially protected or exposed waters must be designed to satisfy the following equation:

$$\frac{0.1(W)B}{(As)(Hc)} \ge X$$

Where-

 $B \!\!=\! the$ distance between hull centerlines in meters (feet).